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2 An implicit loop method for kinematic calibration and its application to closed-chain mechanisms

Wampler, C.W.; Hollerbach, J.M.; Arai, T.
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3 A new Jacobian formulation for general six-revolute manipulators

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Min Gyu Park; Jae Hyun Jeon; Min Cheol Lee;
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Yong K. Hwang, Narendra Ahuja

ACM Computing Surveys (CSUR) September 1992

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